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(71) Applicant: International Business Machines  
 Corporation

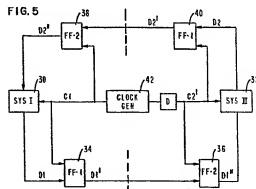
Armonk, N.Y. 10504(US)

(72) Inventor: Flemming, Donald Clyde  
 Mountain View Road  
 Rhinebeck New York 12572(US)

(74) Representative: Lancaster, James Donald  
 IBM United Kingdom Patent Operations Hursley Park  
 Winchester Hants SO21 2JN(GB)

(54) Data transfer apparatus.

(57) Data can be transferred across an interface between a computer processor (30) and a computer channel (32) by an associated pair of latches (34, 36 or 40, 38) for each direction of data flow. The integers on each side of the interface are supplied with a respective appropriate clock ( $C_1$  or  $C_2$ ). The clocks are dissimilar and non-harmonic, with periods  $T_1$  and  $T_2$  such that  $T_1/T_2$  is a rational number, and are offset by a delay circuit (D) by an amount less than  $T_1/\alpha$  from the relationship in which simultaneous transitions would occur,  $\alpha$  being the highest common factor of  $T_1$  and  $T_2$ , and  $\alpha T_1$  being the synchronisation period of the two clocks.



## DATA TRANSFER APPARATUS

Introduction

The present invention relates to the transfer of data across an interface between parts of associated apparatus with dissimilar non-harmonic clocking rates. For example the parts can be parts of a computer system linked by latches on either side of the interface, and the invention can avoid metastability in the latches.

Background of the Invention

An error condition may exist at the interface of two systems each of synchronous logic but with dissimilar and asynchronous clocking rates because of what is commonly referred to as the metastable latch problem. In a bistable latch where the coincidental occurrence of two pulses is required to change the state of the latch, an anomalous failure mode may occur when the two actuating pulses do not overlap sufficiently to cause the latch to completely switch from one of its stable states to the other. With such insufficient overlap of the two actuating pulses, the output or outputs of the latch do not go to either one of the stable up or down levels but actually perturbate at or around a third level referred to as the metastable level. The metastable level is exactly half way between the up and down levels, and when metastability occurs, the latch outputs either momentarily sit at the metastable level before randomly changing to a stable up or down level or alternatively they oscillate around this metastable level.

In latches actuated by signals from two different logic systems running under different and asynchronous clocking rates, the metastable latch problem arises because the clock pulse of one of the systems overlaps, captures or samples an insufficient portion of the data signal from the other system. It is particularly difficult to correct metastability in the transfer of data between two asynchronous systems because the phase of the data signals of each of the two systems is continuously changing with respect to the clock pulses of the other system.

As far as it is caused by differences in clocking rates the metastable latch problem can be solved with known techniques, by running both interfacing systems, from a single clock or two synchronised clocks, at the same clocking rate or at harmonically related clocking rates. However, using the same clocking rate or a harmonic relationship between the two clocking rates is not always a practical solution in any given situation, since it may not allow either system to run anywhere near its optimum operating rate. What is needed is a relationship between the two clocking rates that would allow each of the interfacing systems to approach its maximum performance level while providing the reliable data transfer across the interface.

The solution according to the invention is given in claim 1.

Figure 1 is a block diagram of a simple latch along with diagrams of input and output pulses of the latch which illustrate the metastable condition.

3  
-4-

Figure 2 is a graph illustrating the relationship between a system clock and a subsystem clock in an nonsynchronously operated computer system.

Figure 3 is a graph showing the hatched square in  
5 Figure 2 in greater detail to illustrate the manner in which nonsynchronous clock rates are selected in accordance with the present invention.

Figures 4a to 4c show pulse synchronous and associated waveforms showing desirable mutual  
10 properties of the clocks obtained by selecting the clocks in accordance with the present invention.

Figure 5 is a schematic diagram computer system using the clocking scheme of the present invention, and

15 Figure 6 is a block diagram of the phase lock loop system for generating two clocks in accordance with the present invention.

#### DETAILED DESCRIPTION

Referring to Figure 1, the metastable latch  
20 condition occurs in the latch 10 when two pulses  $D_1$  and  $C_2$ , whose coincidental occurrence is necessary for the setting of the state of the latch 10, do not occur with sufficient overlap 12 for the flip flop 14 of the latch to fully switch from one state to another.  
25 This causes the latch 10 to drop into what is referred to as the metastable state. In the metastable state, the outputs  $Q$  and  $\bar{Q}$  of the latch are neither at a stable up (1) or down (0) level but instead both are at a third level half way between the 0 and 1 levels.

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This third level is undecipherable by other circuits in the system causing an error condition to exist.

As can be seen, when the system clock  $C_2$  is rising just as a data signal  $D_1$  rises, an insufficient amount of the data signal  $D_1$  is sampled during the clock pulse  $C_2$  to properly activate the flip flop 14. The flip flop 14 being confused by the signals momentarily drops into the metastable state causing both outputs of the latch to go to a level  $m$  half way between the up and down levels of the flip flop. Eventually, the flip flop 14 randomly assumes one of its two stable states which may or may not be the correct stable state. The phasing of the two input pulses, illustrated in Figure 1, can arise for a number of reasons. However, the reason we are concerned with here is the constant changing in the phase between the two pulses  $C_2$  and  $D_1$ , which occurs when these pulses are from different systems of synchronous logic with dissimilar and asynchronous clocking rates.

One way of eliminating this cause of metastability, with known techniques, involves making the clocking rates of the two systems the same and providing them from a single pulse source or from two synchronized sources. Another approach is to operate one clock at a harmonic frequency of the other and again supply them from a single source or two synchronized sources. However, either of these approaches may not be the best solution in a particular situation.

The problem with always using the same or harmonically related clocks can be better understood by reference to Figure 2 where the numbers along the

S  
-S-

ordinate represent possible subsystem clock periods  $T_2$ , while the numbers along the abscissa represent possible system periods  $T_1$ . Assume now that in the system under discussion, the most efficient and fastest operation of subsystems is with the period of the subsystem clock set at about 24 nanoseconds, while the most efficient and fastest operation of the system is with the period of the system clock set at about 19 nanoseconds. With these constraints, it is obvious that we can run the system clock at 24 nanoseconds, or in other words the same speed as the subsystem clock, but we could not run the system clock at 12 nanoseconds which would be the first harmonic of the subsystem clock. However, it is possible with the techniques of the present invention to operate the system clock with a period shorter than 24 nanoseconds and longer than 12 nanoseconds without incurring metastability caused by asynchronous operation of the two clocks  $T_1$  and  $T_2$ .

The hatched out area in Figure 2 defines the concurrence of the acceptable ranges of operation of the two clocks. In accordance with the present invention, the operating periods of the two clocks is selected to be within this region of concurrence along one of the lines S radiating out from the zero point on the graph between the fundamental and first harmonic lines. These radiating lines have a slope,

$$S = \frac{T_2}{\alpha} / \frac{T_1}{\alpha} \text{ where } S \text{ is a rational number (i.e.,}$$

$$\frac{T_2}{\alpha} \text{ and } \frac{T_1}{\alpha} \text{ are integers) and } \alpha \text{ is the largest common}$$

$$\text{denominator of } T_1 \text{ and } T_2 \text{ or } \alpha = \frac{|T_2 - T_1|}{|s_n - s_d|} \text{ and } S = \frac{s_n}{s_d}.$$

**BAD ORIGINAL**

6

-7-

Figure 3 shows the hatched area in Figure 2 in more detail with the ratio  $T_1 / T_2$  shown at the top of each radiating line S and various values of  $\alpha$  indicated, along each line S. While S is a rational number, there are only a finite number of different pulse phase relationships between  $C_1$  and  $C_2$  before the relationships repeat themselves. In effect, two pulse trains represented by  $C_1$  and  $C_2$  precess at the rate of  $\alpha$  time units per cycle. For any two periods  $T_1$  and  $T_2$  with an S which is a rational number, the number of such phase relationships, relative to the clock period of interest,  $T_n$ , is equal to  $\frac{T_n}{\alpha}$ . As an

example, assume that the period of the channel clock is set to be 25 nanoseconds, then in accordance with the present invention, the period of the processor clock is selected from the graph of Figure 3 to be 20 nanoseconds. By definition,  $\alpha$  then would be 5.

As shown in Figure 4a, only four different transition positions occur during any period of the clock  $C_1$ ,  $C_2$ . Similarly, there are only five different positions in which the leading edge transition of clock  $C_1$  can occur during any period of clock  $C_2$ . These positions occur at 5 nanosecond intervals meaning that there are 5 nanosecond intervals, or "windows" in which the leading edge transition of one clock pulse will never occur during any given period of the other clock. By delaying one clock by  $\alpha/2$  time units with respect to the other, we can move these intervals or windows so they will occur at the time of a critical transition.

$C_2'$  is the waveform for  $C_2$ , delayed by  $\alpha/2 = 2.5$  nanoseconds, such that alignment of the two clock



7  
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critical (in this case, trailing) edges is avoided for all pulse pair combinations. The relationship between clock pulse sequences repeats every,  $T_2/\alpha = 5$  pulses of  $C_1$  or  $T_1/\alpha = 4$  pulses of  $C_2'$  and precession  
5 between the pulse trains is at the rate of  $\alpha = 5$  nanoseconds per cycle.

In Figure 4b, two closely coupled master-slave flip flops, FF-1 and FF-2, are used to transfer data signals ( $D_2$ ) from a system clocked by  $C_2'$  to a  
10 system clocked by  $C_1$ . The flip flops FF1 and FF-2 are of the type shown in Figure 9.21 and described beginning on page 233 of a book entitled "Introduction to Switching Theory & Logical Design", Second Edition, by Fredrick J. Hill and Gerald R. Peterson, published by  
15 John Wiley & Son, New York in 1974. These flip-flops are designed for trailing edge actuation between master and slave sections. Edge actuation flip flops such as the master slave flip flop are used to avoid metastability problems with other combinations of  
20 critical edges than those aligned in accordance with the present invention. Signal  $D_2$  may arrive at FF-1 anytime during a  $C_2'$  cycle and may persist for one or more of the  $C_2'$  cycles. At the output of FF-1,  $D_2$  has been retimed to one of the critical edges of  $C_2'$   
25 ( $a'$ ,  $b'$ , etc...) such that transitions of  $D_2'$  are not coincident with critical edges of  $C_1$  ( $a$ ,  $b$ , etc...). Thus, after  $D_2'$  retimed in FF-2 by  $C_1$ ,  $D_2''$  is generated at one of the times shown depending on which  $C_1$  pulse samples  $D_2'$ . In the case where  $C_1$  edge 'e'  
30 performs the sampling, edge 'a' will resample the same  $D_2'$  signal one  $C_1$  cycle later, resulting in the two cycle minimum output pulse shown. Transfers conducted by all other combinations of edge pairs will result in one cycle minimum pulses out, as shown.

9  
-8-

Figure 4(c) shows corresponding relationships for transfers from a system clocked by  $C_1$  to a system clocked by  $C_2$ . Since  $C_2$  has a longer period than  $C_1$ , oversampling of  $D_1$  is not possible, but undersampling would occur if a one cycle  $D_1$  pulse were to arrive between  $C_1$  edges 'e' and 'a'. To prevent missing this event, all  $D_1$  pulses must have a minimum width of two cycles. Then  $D_1$  will be two cycles minimum duration except for an input pulse rising with edge 'e'. This will not be sampled by  $C_2$  until edge 'a' arrives, resulting in the one cycle output pulse shown.

In Figure 5, a synchronizer is shown for transferring clocked data bits back and forth between the processor 30 and the channel 32 one bit at a time. The synchronizer is formed of the two sequences of the type discussed in connection with Figure 4 in each direction making a total of four clocked master slave flip flops 34 to 40. Each of these flip flops receives a data signal from one or the other of the systems, and a clock pulse from a clock generator 42, which will be described hereinafter. Transmission delays of various amounts are involved in the transmission of the clock pulses and the data registers. These delays must be taken into account to avoid metastability due to these delays. However, some compensation on such delays is well known in the prior art. They are disregarded here for simplicity and understanding of the present invention.

Assume we have the situation described in Figure 1, where the data signal  $D_1$  is being transmitted from system 1 or the processor to system 2 or the channel. Then the data signal is fed into a first latch 34 along with the clock  $C_1$  to set the latch 34 and the clock  $C_1$

9  
-18-

is used to reset the latch. The trailing edge of the output pulse  $D_1'$  of latch 34 is therefore fixed to coincide with the trailing edge of the clock pulse  $C_1$ . The output pulse  $D_1'$  is fed to the input of latch 36 along with the clock  $C_2'$ , where the phasing at the inputs is set to be as previously described and shown in Figure 4 by the relationship between curves  $D_1$  and  $C_2'$ .

In the real systems of course, the window would not actually be a full 5 nanoseconds. Consideration must be given to deviations in the occurrences of the pulses from system to system because of manufacturing tolerances and within each system depending on design and implementation options.

The clock generator 42 in Figure 5 is shown in more detail in Figure 6. As can be seen, it contains a phase lock loop. The function of the phase lock loop is to provide a phase and frequency relationship between clock pulses  $C_1$  and  $C_2$  for the processor and channel systems respectively. The phase lock loop consists of four basic components, the voltage controlled oscillator 50, the frequency divider 52, phase frequency comparator 54 and a low pass filter. The input to the phase lock loop is from an oscillator 56 which generates the clock signal  $C_1$  for the processor. The frequency of oscillation of the oscillator is set at  $F_1 = \frac{1}{T_1}$ .

The output of the oscillator is divided by  $T_2/\alpha$  in divider 58 before being fed to the phase/frequency comparator 54. The frequency phase comparator 54 compares the output of divider circuit 58 with the

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-11-

- output of divider circuit 52 which divides the output of the voltage controlled oscillator 50 by  $T_1$  /  $\omega$  . This is to determine if the voltage controlled oscillator 50 is tracking the oscillator 56. This is
- 5 done by comparing the positive transition of circuit 58 to the positive transition of the frequency divider 52. If the reference is early, the output of the comparator 54 switches to a down level. If the reference is late, the output goes to a high level.
- 10 The filter smoothes out the comparator output so that the output frequency of the voltage controlled oscillator only follows long term changes in the reference signal phase. The output of the voltage controlled oscillator is the channel clock  $C_2$ .
- 15 Above, we have described one embodiment of the invention. In this embodiment, the two periods  $T_1$  and  $T_2$  were fairly arbitrarily selected. However, in real applications, other considerations could put constraints on the values that can be selected.
- 20 Generation of the time of day clock requires that the value of the system clock  $C_1$  be set at specific values, one of which may or may not be 20 nanoseconds. In any case, it is quite easy to change the system clock  $C_1$  from 20 nanoseconds to say 20.94 nanoseconds
- 25 as required by the time of day clock, and then select a channel clock of 26.18 nanoseconds instead of 25 nanoseconds and still obtain full advantage of the present invention. Therefore, it should be understood that while a single embodiment of the invention has
- 30 been described, many changes in this embodiment can be made without departing from the spirit and scope of the invention, as set forth in the claims attached hereto.



CLAIMS

1. Data transfer apparatus in which data is transmitted across an interface (Fig. 5) between parts (30, 32) of the apparatus operated under the control of two clocks ( $C_1$ ,  $C_2$ ) with different frequencies, the clocks having two mutually non-harmonic frequencies whose periods  $T_1$  and  $T_2$  form a ratio

$$\frac{T_2/\alpha}{T_1/\alpha} = S$$

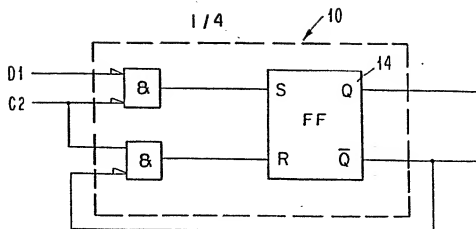
that is a rational number,  $\alpha$  being the highest common factor of  $T_1$  and  $T_2$ , so that there is a limited number of transitions of the pulses of each clock before pulse relationships of the two clocks are repeated, with a period  $\alpha T_n$ , the two clocks being offset by an amount less than  $T_n$  from the relationship in which simultaneous transitions would occur.

2. Apparatus as claimed in claim 1 in which the two clocks comprise a first oscillator (56) and a second voltage controlled oscillator (50) operating respectively at  $f_1 = \frac{1}{T_1}$  and  $f_2 = \frac{1}{T_2}$ , the second oscillator being synchronised with the first by phase lock loop circuitry (Fig. 6).

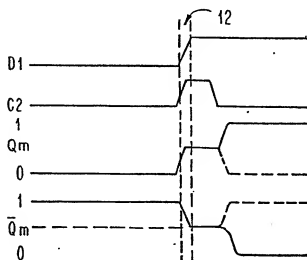
3. Apparatus as claimed in claim 2 in which the two clocks are offset by delay circuitry (D, Fig. 5).

4. Apparatus as claimed in claim 3 in which said delay circuitry (D) is connected to the output of the second oscillator.

5. Apparatus as claimed in any preceding claim in which a pair of latches (38, 40; 34, 36) is provided for each direction of data flow across the interface, each latch of a pair receiving a respective one of the clocks ( $C_1$ ,  $C_2'$ ).



**FIG. 1**  
PRIOR ART



**FIG. 2**

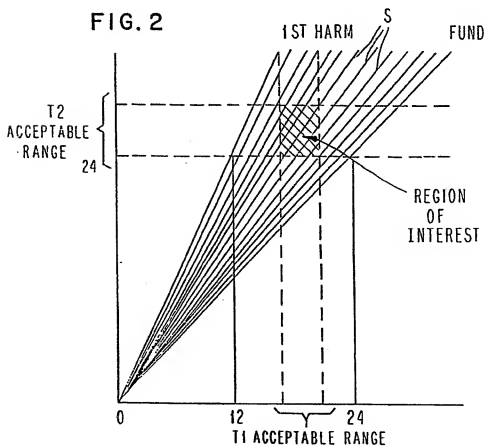


FIG. 3

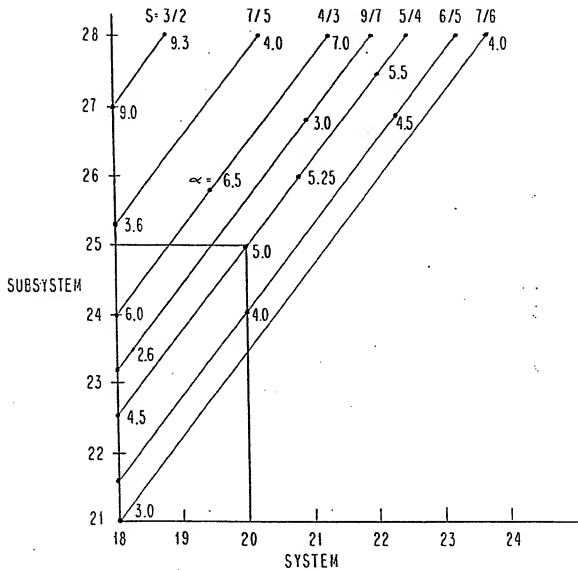


FIG. 6

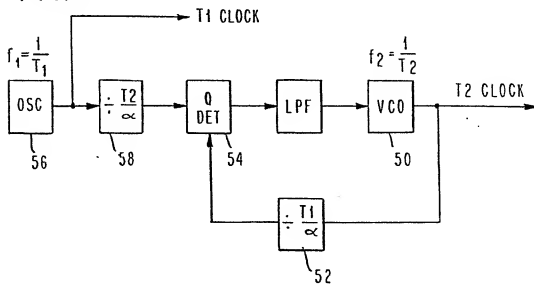




FIG. 4a

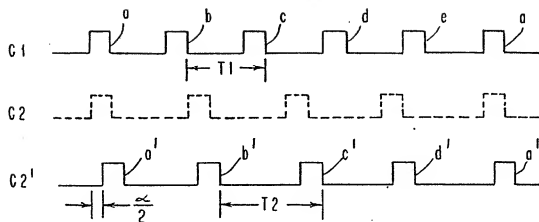
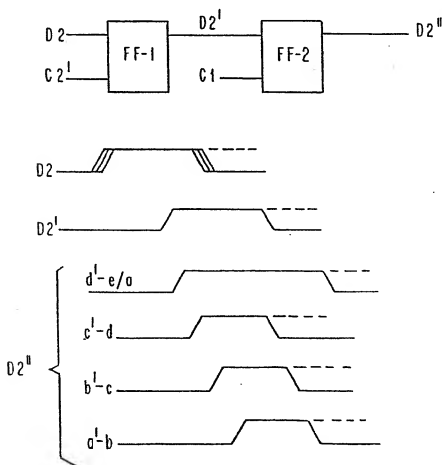


FIG. 4b



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FIG. 4C

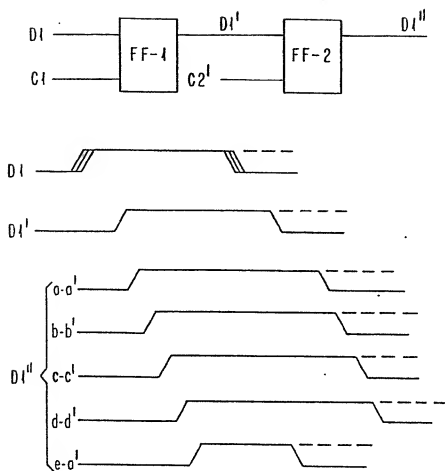
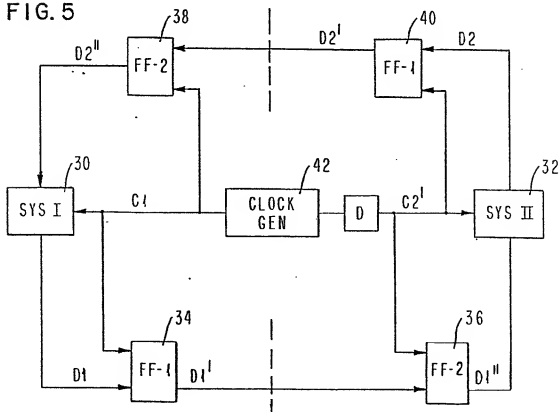


FIG. 5





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# EUROPEAN PATENT APPLICATION

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71 Applicant: International Business Machines Corporation,  
Armonk, N.Y. 10504 (US)

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72 Inventor: Flemming, Donald Clyde, Mountain View Road,  
Rhinebeck New York 12572 (US)

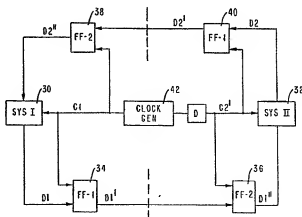
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74 Representative: Lancaster, James Donald, IBM United  
Kingdom Patent Operations Hursley Park, Winchester  
Hants SO21 2JN (GB)

## 54 Data transfer apparatus.

57 The transfer of data across an interface between a computer processor (30) and a computer channel (32) by an associated pair of latches (34, 36 or 40, 38) for each direction of data flow. The parts on each side of the interface are respectively supplied with an appropriate clock signal ( $C_1$  or  $C_2^1$ ). The clocks are dissimilar and non-harmonic, with periods  $T_1$  and  $T_2$  such that  $T_1/T_2$  is a rational number, and are offset by a delay circuit (D) by an amount less than  $T_n/\alpha$  from the relationship in which simultaneous transitions would occur,  $\alpha$  being the highest common factor of  $T_1$  and  $T_2$ , and  $\alpha T_n$  being the synchronisation period of the two clocks.



DOCUMENTS CONSIDERED TO BE RELEVANT			CLASSIFICATION OF THE APPLICATION (Int. Cl.)
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	
X	IBM TECHNICAL DISCLOSURE BULLETIN vol. 17, no. 7, December 1974, New York, US DUKE: "Multiple frequency clocking system", pages 2046-2049 * Whole article *	1,2	G 06 F 1/04 H 03 L 7/18
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X	IBM TECHNICAL DISCLOSURE BULLETIN vol. 10, no. 11, April 1968 New York, US TSUI: "Use of derived timing pulses in I/O devices", page 1808 * Whole article *	1	
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	NEC RESEARCH & DEVELOPMENT, no. 53, April 1979, Tokyo, JP KUSAMA et al. "Tunable phase- locked oscillator with digital frequency divider" pages 56-61. * From page 56, right-hand column, line 11 to page 57, left-hand column, line 16 *	2	TECHNICAL FIELDS SEARCHED (Int. Cl.)  G 06 F 1/04 H 03 K 3/13 H 03 L 7/18
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	<u>US - A - 3 217 267 (LOPOSER)</u> * From column 11, line 67 to column 12, line 58 *	1,2	CATEGORY OF CITED DOCUMENTS  X: particularly relevant A: technological background O: non-written disclosure P: intermediate document T: theory or principle underlying the invention E: conflicting application D: document cited in the application L: citation for other reasons
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A	<u>US - A - 3 740 590 (HART et al.)</u> * From column 1, line 1 to column 2, line 13 *	1,3	
	-- ./.		
<div>  The present search report has been drawn up for all claims </div>			&: member of the same patent family, corresponding document
Place of search	Date of completion of the search	Examiner	
The Hague	12-10-1981	LACROIX	



European Patent  
Office

# EUROPEAN SEARCH REPORT

0042924  
Application number  
EP 81 10 2943  
-2-

DOCUMENTS CONSIDERED TO BE RELEVANT			CLASSIFICATION OF THE APPLICATION (Int. Cl. 7)
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	
A	ELEKTRONIK, vol. 25, no. 9, September 1976 Munich, DE DIRKS et al. "Taktgenerator für Mikroprozessor 6800" page 71 * Whole article *	1,3	
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			TECHNICAL FIELDS SEARCHED (Int. Cl. 7)

